Dual displacement motor A10VEC

Compact version for track- and wheel drive in open circuit Series 52, Axial piston, Swash plate design

Brueninghaus Hydromatik

REXROTH

MANNESMANN

Size 45

Nominal pressure 280 bar Peak pressure 350 bar

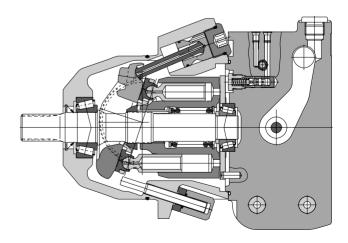
RE 91710/03.97

Fixed displacement motor A10FM and fixed displacement plug-in motor A10FE see RE 91172

Dual displacement motor A10VM and plug-in motor A10VE see RE 91703



- Proven A10-rotary group
- Heavy duty bearings for long service life
- High permissible output speed
- High power/weight ratio-compact size
- Low noise
- Hydraulic connections to SAE-standards
- Control range 1: 3,75
- External direct control supply possible
- Minimum displacement externally adjustable
- Special 2-bolt flange
- Space saving through integrated valves



Dual displacement motor A10VEC, Series 52														
Ordering code											<u> </u>			_
	A10V	EC	45	/ /	52	W		-		R	F			
Fluid														
Mineral oil (no code)														
Axial piston unit														
Swash plate design, variable Nom. press. 280 bar, Peak press. 350 bar	A10V													
Operating														
Plug-in motor, variable, compact design	n E	C												
Size			_											
Displacement V _{g max} (cm ³)		45	5											
Control devices Hydraulical two-point control	HZ		HZ	_										
Direct control pressure	DG		D0											
without pilot valve														
Series					2									
Direction of rotation					2									
Direction of rotation Viewed on shaft end		bi-	directio	nal	V	v								
Minimum displacement														
stepless adjustable $V_{gmin} = 12 \text{ cm}^3 \text{ to } V_{gr}$						—								
Example 12 cm ³ - please state when or	dering					12	2							
Seals NBR (Nitrile caoutchouk DIN ISO 1629)) with shaft s	sealring	1 FPM					Р						
FPM (Fluor caoutchouk DIN ISO 1629)	,		,					V						
Shaft end														
SAE-splined									R					
Mounting flange									F					
Special 2-bolt mounting flange														
Service line connections Ports A/B SAE-flange at side (same sid	e), UNC-thr	eaded	bolt hol	es:										
various valves integrated, see page 7								0	7	1				
Ports A/B SAE-flange at side (same sid various valves integrated, see page 7				les;				ullet	2	1				
Ports A/B at side (same side), SAE-O-F various valves integrated, see page 7	Ring threade	ed ports	s UNF;					•	8	1				
	••													
Pressure range of pressure relief valve	es								1					
320 bar 350 bar									2					
										C) = in	prep	parat	ion
) = A	vaila	ble	

Technical data

For extensive information on the selection of fluids and for application conditions, please consult our data sheets RE 90220 (mineral oils) or RE 90221(environmentaly accetable hydraulic fluids).

You might have to consider reduced operating data with environmentaly accetable hydraulic fluids. Please contact our technical department.

Operating viscosity range

In order to obtain optimum efficiency and service life, we recommend that the operating viscosity (at operating temperature) be selected from within the range:

 $v_{oot.}$ = Operating Viscosity 16...36 mm²/s

referred to the tank temperature (open circuit).

Viscosity limits

The limiting values for viscosity are as follows:

- $v_{min} = 10 \text{ mm}^2/\text{s}$ short term at a maximum permissible drain temperature of 90° C.
- $v_{max} = \frac{1000 \text{ mm}^2/\text{s}}{\text{short term on cold start}}$

Temperature range (see selection diagram)

 $t_{min} = -25^{\circ} C$ $t_{max} = 90^{\circ} C$

Notes on the selection of the hydraulic fluid

In order to select the correct fluid, it is necessary to know the tank temperature (open circuit) in relation to the ambient temperature. The hydraulic fluid should be selected so that within the operating temperature range, the operating viscosity lies within the optimum range (v_{opt}) (see shaded section of the selection diagram). We recommend that the highest possible viscosity range should be chosen in each case.

Example: At an ambient temperature of $X^{\circ}C$, the operating temperature is 60°C. Within the operating viscosity range (vopt; shaded area), this corresponds to viscosity ranges VG 46 or VG 68. VG 68 should be selected.

Important: The leakage oil (case drain oil) temperature is influenced by pressure and pump speed and is always higher than the tank temperature. However, at no point in the system may the temperature exceed 90°C.

If it is not possible to comply with the above conditions because of extreme operating parameters or high ambient temperatures, please consult us.

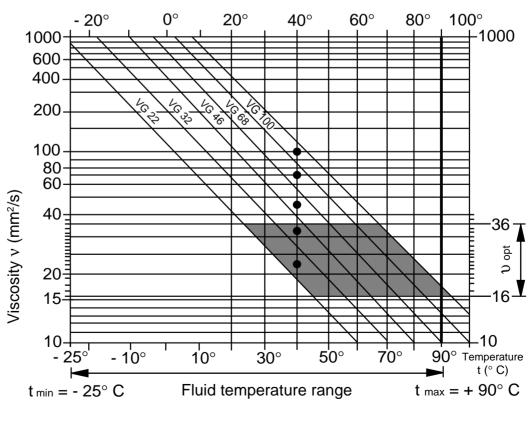
Filtration of fluid

In order to ensure correct functioning of the unit, a minimum level of cleanliness to NAS 1638 class 9,

to SAE; ASTM, AIA class 6 or

to ISO/DIS 4406 class 18/15 is required. If it is not possible to comply with the above conditions, please consult us.

Selection diagram



Technical Data

Operating pressure range Pressure at ports A or B Nominal pressure p_N 280 bar Peak pressure p_{max} (Pressure data to DIN 24312) 350 bar

Caise drain pressure

Max. permissible pressure at ports L,L,

p abs max -

Direction of rotation

Flow B to A = Clockwise Flow A to B = Counter-clockwise

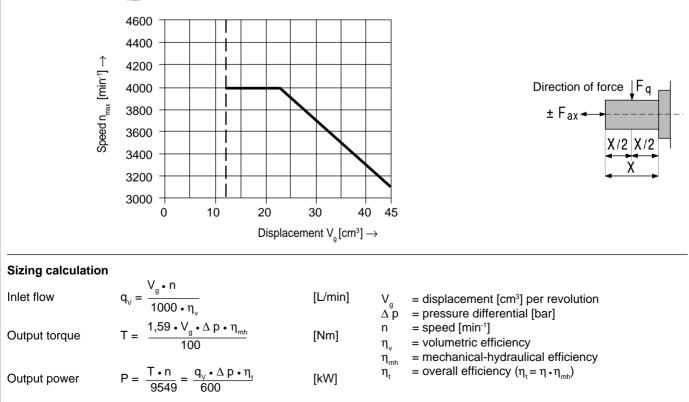
Displacement

The minimum displacement is factory set in accordance with the ordering code.

Table of values (theoretical values, without considering $\eta_{\text{ mh}}$ and $\eta_{\text{ v}}\!;$ values rounded)

Size				45
Displacement		V _{g max}	cm ³	45
		V _{g min}	cm ³	12
Speed ¹) (see diagram)	at V _{g max}	n _{max}	min ⁻¹	3100
	at V _{g min}	n _{max1}	min ⁻¹	4000
Max. inlet flow	at n_{max} und $V_{g max}$	q_{Vmax}	L/min	140
Max. output power ($\Delta p = 280$ bar)	at n_{max} und $V_{g max}$	P _{max}	kW	65
Max. torque ($\Delta p = 280$ bar)	at V _{g max}	T _{max}	Nm	200
Moment of inertia about drive axis		J	kgm ²	0,0033
Filling volume			L	0,7
Weight		m	kg	17
Permissible loading on drive shaft	max. perm. axial load	F ax max	Ν	1500
	max. perm. radial load	F _{q max}	Ν	1500
Actual starting torque ($\Delta p = 280 \text{ bar}$)	at n = 0 min ⁻¹	•	Nm (approx.)	138

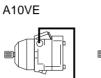
¹) determination of n _{max}



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Mounting position

Is optional. The motorhousing must be filled with oil during commissioning operation. Install drain line in such a manner that housing cannot empty during stand still, i.e. make sure drain line ends below min. fluid level. The port, located at the highest point should be used for filling the housing and for connecting the drain line.







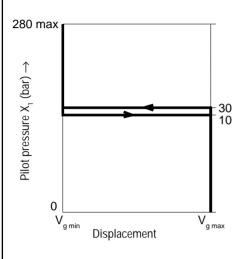
2 bar

Hydraulical two-point control, HZ

Normally, the motor is at max. displacement. By applying a pilot pressure to port X, the destroking piston is pressurized and the motor switches to minimum displacement.

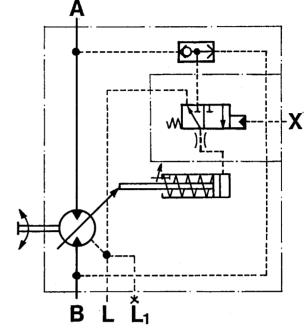
The necessary control pressure is via a shuttle valve, taken out of the port A or B.

The minimum required control pressure is ≥ 20 bar. Only max. and min. displacements are possible.



= 0 bar

≥ 30 bar



Circuit diagram

Technical data HZ

Pilot pressure in X

Pilot pressure in X

minimum pilot pressure	30 bar
maximum perm. pilot pressure	280 bar

 $= V_{a \max}$

 $= V_{g \min}$

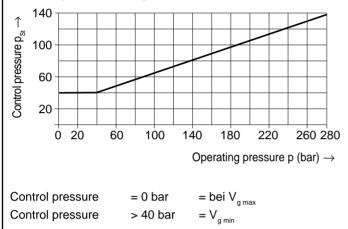
Direct control pressure, DG

Normally, the motor is at max. displacement. By applying a external pressure to port G, the destroking piston is directly pressurized and the motor swithes to minimum displacement. The minimum required control pressure is ≥ 40 bar.

This control pressure depends directly on the working pressure in A or B.

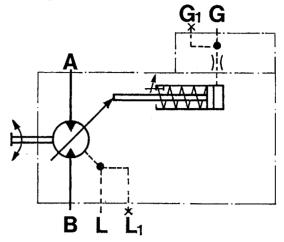
See control pressure diagram below. With a control pressure above this minimum required pressure level the motor will destroke properly.

Control pressure diagram



Max. perm control pressure amounts to $p_{st} = 280$ bar.

Circuit diagram



With integrated valves for motion control, crossover pressure relief - and brake release functions

Brake release function (Item 1)

The motor has a connection Bri. This connection enables the release of a gearbox - mounted parking brake. An integrated switching valve leads system pressure from "A" or "B" to a pressure reducing valve, which limits max. brake release pressure to 30 bar.

Motion control valve (Item 2)

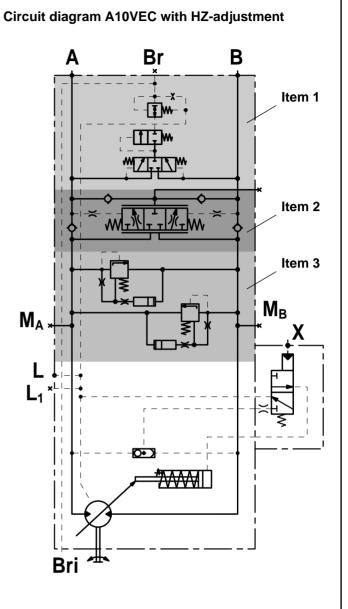
When going downhill, the motion control valve prevents the motor from overspeeding and thus from a run-away condition. This can happen if motor operation turns into a pump, due to external forces.

The valve spool opens only at a certain pre determined pressure in the inletflow side of the motor and enables thus unit to start moving. If pressure on the motor inlet side should drop due to speed increases or inlet flow, the spool shifts gradually to centre position causing a braking face of mounting flange action. In centre position high pressure ports A and B are nearly closed leaving only a small residual passage. This motion control function operates in both directions of rotation.

Pressure relief valve (Item 3)

These valves limit the max. pressure, and prevent damage to the motor. Both directions of rotation each have a relief valve. Each valve opens to the opposite side of the motor (cross over valves). Dampening the valve action causes a soft operation, and avoids jerky machine movements.

Please denote the correct vave pressure setting in the ordering code, page 2.



66

1.0

50

Bri

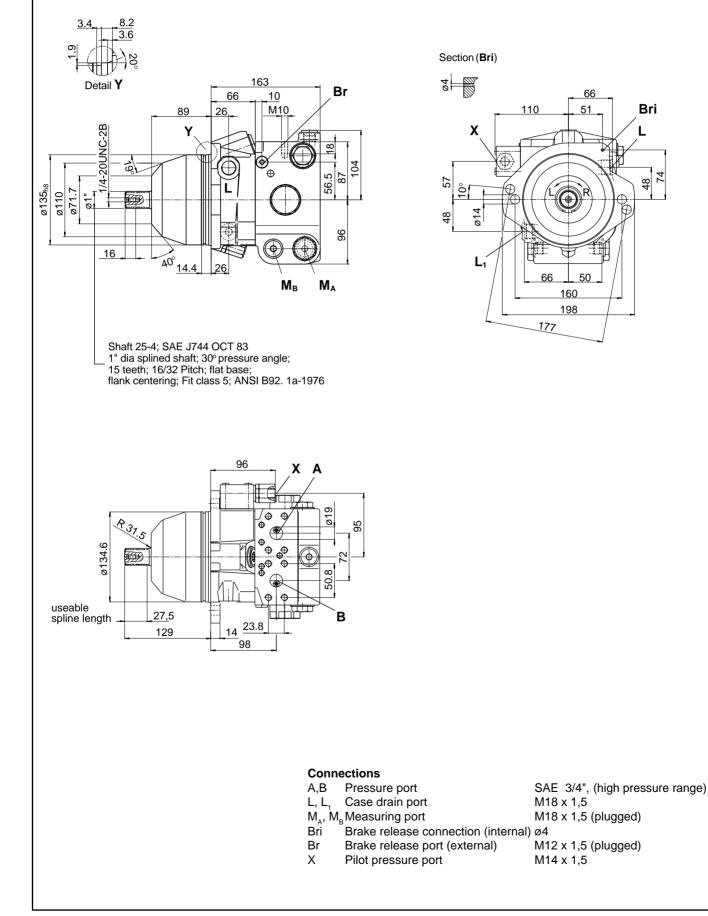
7

48

L

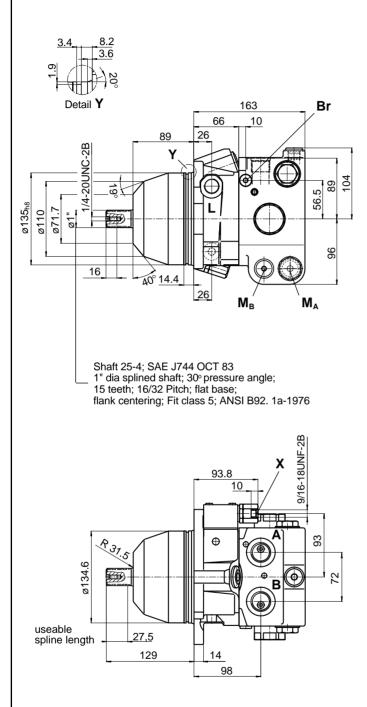
51

Unit dimensions A10VEC 45 HZ /52 W XX-PRF 21 X with port plate 21

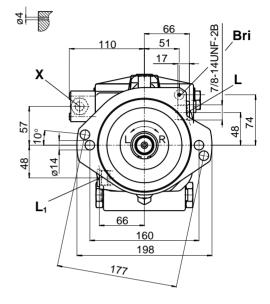


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Unit dimensions A10VEC 45 <u>HZ</u> /52 W XX-PRF <u>81</u> X with port plate 81



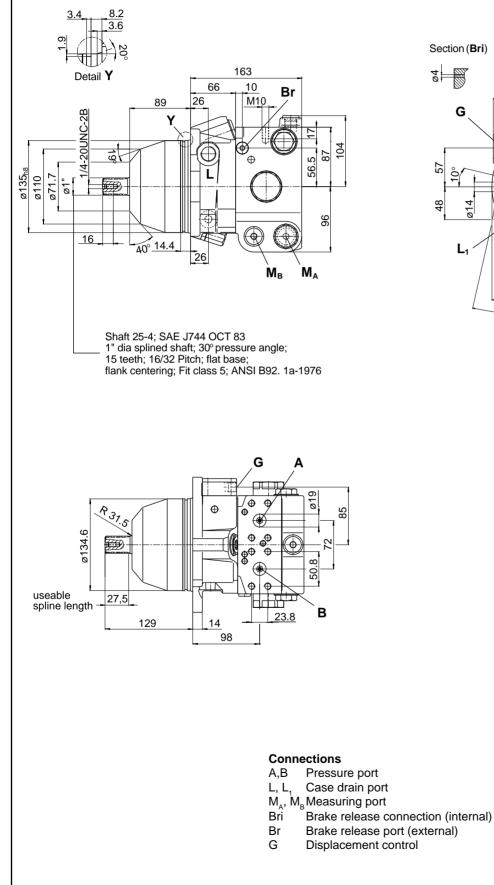
Section (Bri)

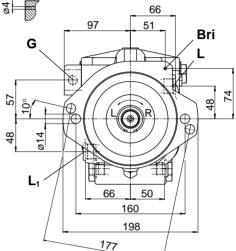


Connections

A,B	Pressure port	1 1/16-12 UN-2B
L, L,	Case drain port	7/8-14 UNF-2B
M _A , M _B	Measuring port	M18 x 1,5 (plugged)
Bri	Brake release connection (internal)	ø4
Br	Brake release port (external)	M12 x 1,5 (plugged)
Х	Pilot pressure port	9/16-18 UNF-2B

Unit dimensions A10VEC 45 DG /52 W XX-PRF 21 X with port plate 21





SAE 3/4", (high pressure range) M18 x 1,5 M18 x 1,5 (plugged) Ø4 M12 x 1,5 (plugged) M14 x 1,5

Notes on other items in the medium pressure A10 range:

	Variable pump	Size: 28 cm ³	45 cm ³ 71 cm ³ 100 cm ³ 140 cm ³
	A10VO	•	
	series 31	DG	devices: Two-point control, direct control
RE 92701		DG DR	Pressure control
		DRT	Pilot pressure dependent pressure regulator
		DFR	Pressure and flow control
	Variable pump	DFLR	Pressure/flow and power control
	A10VSO	DFSR FHD	Pressure/flow and summary power control Pilot pressure dependent flow control with
		ГПО	pressure cut-off
للحيك	series 31	FE1	Electonic flow control
RE 92711		DFE1	Electonic pressure and flow control
		DS	Speed control, secondary control (RE 92715)
		Size:	
	Variable numn	51ze: 16 cm ³	
	Variable pump		
	A10VSO	DR	devices: Pressure control
	series 31	DFR	Pressure and flow control
RE 92712		DFR1	Pressure and flow control orifice in X-port plugged
		DFE1	Electonic pressure and flow control
ÆØ.		Size:	
	Variable pump	10 cm ³	
	A10VSO	Control	devices:
Ų <u></u> _ <u></u> ⊢_ <u></u> _	series 52	DR	Pressure control
RE 92713		DRG	Pressure control, remote control
		DFR1	Pressure and flow control orifice in X-port plugged
	Variable pump	Size:	
	A10VO	28 - 60 c	cm ³
		0	desite en
	series 52	DR	devices: Pressure control
RE 92703		DFR	Pressure and flow control
for the second second	Fixed displacement motor		
	A10FM		
	series 30		
п		Size:	
	Fixed displacement	23 cm ³	28 cm ³ 37 cm ³ 45 cm ³
	plug-in motor		
<u>محساب برم</u>	A10FE		
RE 91172	series 30		

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